## **IEEE LCN ON-MOVE 2007**

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## Real-time Coordination of Intelligent Vehicles

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This presentation reviews on-going work on the application of mobile and ubiquitous computing to intelligent transportation systems within the Distributed Systems Group at Trinity College Dublin. In particular, we present novel (hard) real-time communication and coordination models that are being developed to support safety-critical mobile applications in dynamic wireless networks, in particular, intelligent and autonomous vehicles. We illustrate their use in the design of an emergency-vehicle warning system that employs real-time feedback on the state of communication to improve achievable emergency-vehicle speed.

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